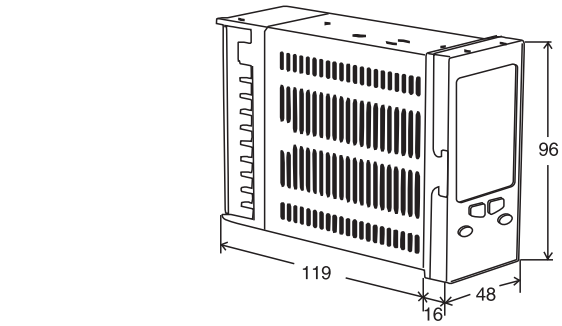
SSi Super Systems

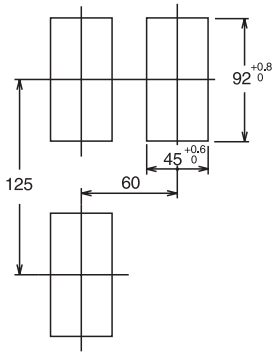
Instruction Manual

31080 (1/8 DIN)
Controller

INDEX

OUTLINE AND CUT OUT DIMENSIONS





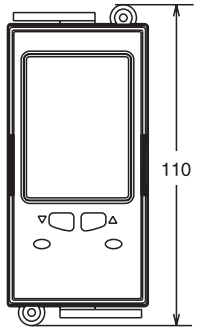


Fig. A1 31080

CONNECTION DIAGRAMS
Connections are to be made with the instrument housing installed in its proper location.

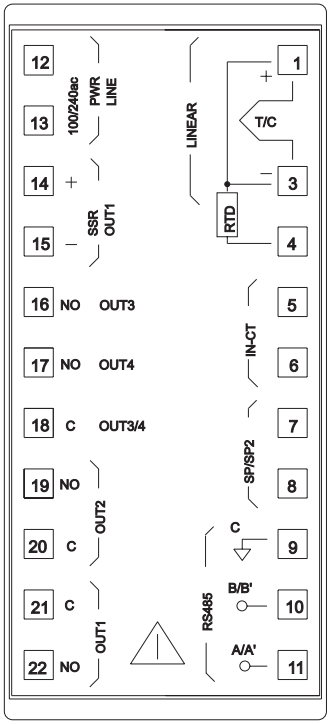


Fig. B

MOUNTING REQUIREMENTS

These instruments are intended for permanent installation, for indoor use only, in an electrical panel which encloses the rear housing, exposed terminals and wiring on the back.
Select a mounting location where the instrument is subject to minimum vibration and the ambient temperature range is between 0 and 50 °C.
These instruments can be mounted on a panel up to 15 mm thick with a square cutout of 45 x 92 mm .
For outline and cutout dimensions refer to Fig. 2.
The surface texture of the panel must be better than 6,3 μm.
The instrument is shipped with rubber panel gasket.
To assure the IP65 and NEMA 4 protection, insert the panel gasket between the instrument and the panel as shown in fig. 1.
While holding the instrument against the panel proceed as follows:
1) insert the gasket in the instrument case;
2) insert the instrument in the panel cutout;
3) pushing the instrument against the panel, insert the mounting bracket;
4) with a screwdriver, turn the screws with a torque between 0.3 and 0.4 Nm.

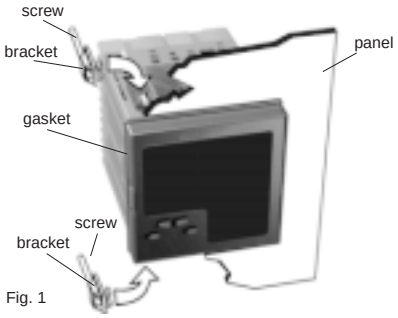


Fig. 1

CONNECTIONS

A) MEASURING INPUTS

NOTE: Any external component (like zener barriers etc.) connected between sensor and input terminals may cause errors in measurement due to excessive and/or not balanced line resistance or possible leakage currents.

TC INPUT

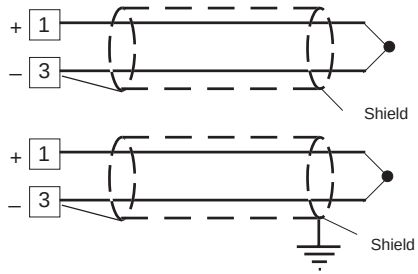


Fig. 2 THERMOCOUPLE INPUT WIRING

External resistance: 100 Ω max, maximum error 0.1% of span.
Cold junction: automatic compensation from 0 to 50 °C.
Cold junction accuracy: 0.1 °C/°C
Input impedance: > 1 MΩ

NOTES:
1) Don't run input wires together with power cables.
2) For TC wiring use proper compensating cable preferable shielded.
3) when a shielded cable is used, it should be connected at one point only.

RTD INPUT

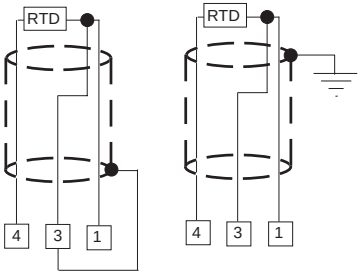


Fig. 3 RTD INPUT WIRING

Input: for RTD Pt 100 Ω, 3-wire connection.
Line resistance: automatic compensation up to 20 Ω/wire with no measurable error.

NOTES:
1) Don't run input wires together with power cables.
2) Pay attention to the line resistance; a high line resistance may cause measurement errors.
3) When shielded cable is used, it should be grounded at one side only to avoid ground loop currents.
4) The resistance of the 3 wires must be the same.

LINEAR INPUT

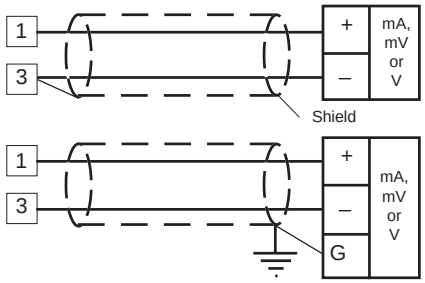


Fig. 4 mA, mV AND V INPUTS WIRING

NOTES:
1) Don't run input wires together with power cables.
2) Pay attention to the line resistance; a high line resistance may cause measurement errors.
3) When shielded cable is used, it should be grounded at one side only to avoid ground loop currents.

Input type		impedance	Accuracy
11	**0 - 60 mV**	> 1 MΩ	0.2 % + 1 digit @ 25°C
12	**12 - 60 mV**		
13	**0 - 20 mA**	< 5 Ω	
14	**4 - 20 mA**		
15	**0 - 5 V**	> 200 kΩ	
16	**1 - 5 V**		
17	**0 - 10 V**	> 400 kΩ	
18	**2 - 10 V**		

B) LOGIC INPUT

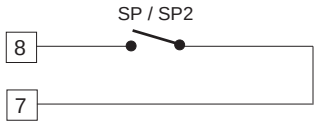


Fig. 5 - LOGIC INPUT WIRING

This logic input allows to select the operative set point.

logic input	op. set point
open	SP
close	SP2

Safety notes:

1) Do not run logic input wiring together with power cables.
2) Use an external dry contact capable of switching 0.5 mA, 5 V DC.
3) The instrument needs 100 ms to recognize a contact status variation.
4) The logic input is **NOT** isolated by the measuring input

CURRENT TRANSFORMER INPUT

This input allows to measure and display the current running through the load, driven by the OUTPUT 1, during the ON and the OFF period of the OUT 1 cycle time.
By this features it is also available the "Out 1 failure detection" function (see page 18)

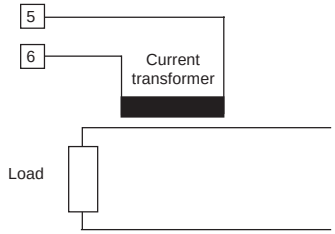


Fig. 6 CURRENT TRANSFORMER INPUT WIRING

NOTES:

1) The input impedance is equal to 10 Ω.
2) The maximum input current is equal to 50 mA (50 / 60 Hz).
3) The minimum period (ON or OFF) to perform this measurement is equal to 400 ms.

Scaling: programmable from 10 A to 100 A (with 1A step).
Resolution:
- for full scale up to 20 A: 0.1 A.
- for full scale from 21 A to 100 A: 1 A

Safety note:

- Do not run current transformer input wiring together with power cables.

C) RELAY OUTPUTS

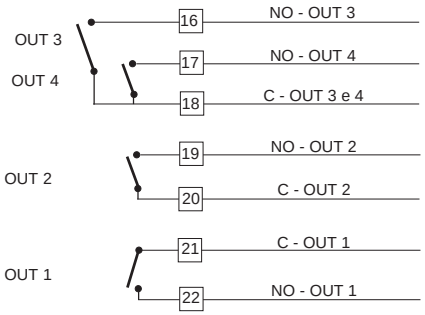


Fig. 7 RELAY OUTPUTS WIRING
The outputs 1 and 2 are protected by varistor against inductive load with inductive component up to 0.5 A.
The contact rating of the OUT 1 is 3A/250V AC resistive load.
The contact rating of the OUT 2, 3 and 4 is 2A/250V AC resistive load.
The number of operations is 1 x 10^5 at specified rating.
NOTES:
1) To avoid electrical shock, connect power line at the end of the wiring procedure.
2) For power connections use No 16 AWG or larger wires rated for at last 75 °C.
3) Use copper conductors only.
4) Don't run input wires together with power cables.
5) Relay output and SSR drive output are both available. For the relay output selection see "Preliminary hardware settings" chapter.

VOLTAGE OUTPUT FOR SSR DRIVE

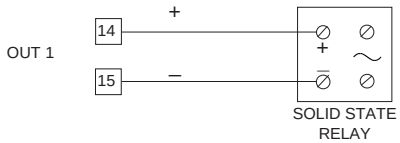


Fig. 8 SSR DRIVE OUTPUT WIRING
It is a time proportioning output.
Logic level 0: Vout < 0.5 V DC.
Logic level 1:
- 14 V ± 20 % @ 20 mA
- 24 V ± 20 % @ 1 mA.
  Maximum current = 20 mA.

NOTES:
1) This output is not isolated. A double or reinforced isolation between instrument output and power supply must be assured by the external solid state relay.
2) Relay output and SSR drive output are both available. For the SSR output selection see "Preliminary hardware settings" chapter.

SERIAL INTERFACE

RS-485 interface allows to connect up to 30 devices with one remote master unit.

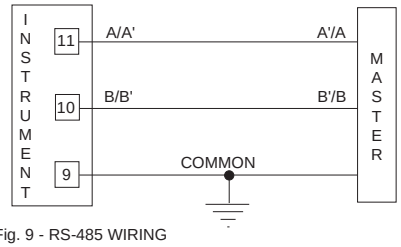


Fig. 9 - RS-485 WIRING

The cable length must not exceed 1.5 km at 9600 BAUD.

NOTES:

1) This is an RS485 isolated interface.
2) The following report describes the signal sense of the voltage appearing across the interconnection cable as defined by EIA for RS-485.
   a) The "A" terminal of the generator shall be negative with respect to the "B" terminal for a binary 1 (MARK or OFF) state.
   b) The "A" terminal of the generator shall be positive with respect to the "B" terminal for a binary 0 (SPACE or ON)

D) POWER LINE WIRING

Fig. 10 POWER LINE WIRING

100V to 240V AC 50/60Hz (-15% to + 10% of the nominal value).
24 V AC/DC (± 10 % of the nominal value).

NOTES:

1) Before connecting the instrument to the power line, make sure that line voltage corresponds to the description on the identification label.
2) To avoid electrical shock, connect power line at the end of the wiring procedure.
3) For supply connections use No 16 AWG or larger wires rated for at last 75 °C.
4) Use copper conductors only.
5) Don't run input wires together with power cables.
6) For 24 V DC the polarity is a do not care condition.
7) The power supply input is **NOT** fuse protected. Please, provide it externally.

Power supply	Type	Current	Voltage
24 V AC/DC	T	500 mA	250 V
100/240 V AC	T	63 mA	250 V

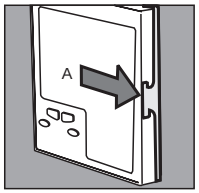
   When fuse is damaged, it is advisable to verify the power supply circuit, so that it is necessary to send back the instrument to your supplier.
8) The safety requirements for Permanently Connected Equipment say:
   - a switch or circuit-breaker shall be included in the building installation;
   - It shall be in close proximity to the equipment and within easy reach of the operator;
   - it shall be marked as the disconnecting device for the equipment.

   NOTE: a single switch or circuit-breaker can drive more than one instrument.
9) When a neutral line is present, connect it to terminal 13.

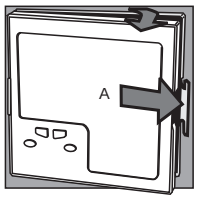
PRELIMINARY HARDWARE SETTINGS

How to remove the instrument from its case

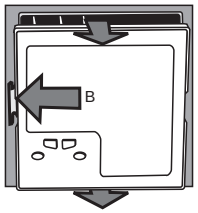
1) Switch off the instrument.
2) Push gently the lock A on the right.



3) While the lock A is maintained out, slide out the right side of the instrument.



4) Push gently the lock B on the left.
5) While the lock B is maintained out, slide out the instrument.



MAIN INPUT SELECTION

If an input different from TC-RTD input (standard) is desired, remove the instrument from its case and set J1 according to the following table.

INPUT	J1				
TYPE	1-2	3-4	5-6	7-8	9-10
TC-RTD	open	close	open	open	open
60 mV	open	close	open	open	open
5 V	close	open	close	open	open
10 V	open	open	close	open	open
20 mA	open	open	open	close	close

NOTE: the jumper not used can be placed on pin 7-9

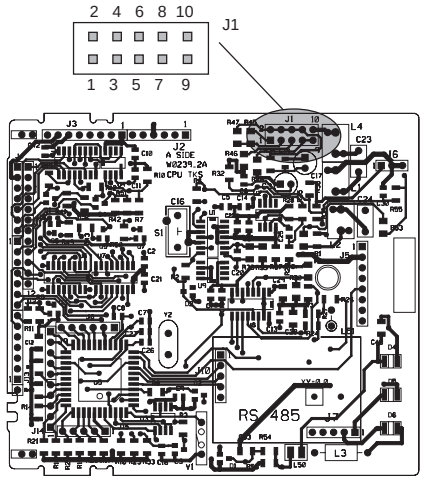


Fig. 11

OPEN INPUT CIRCUIT

This instrument is able to identify the open circuit for TC and RTD inputs.
The open input circuit condition for RTD input is shown as an "overrange" condition.
For TC input, it is possible to select overrange indication (standard) or underrange indication setting the CH2 and SH2 according to the following table:

Overrange (STD)	CH2 = close	SH2 = open
Underrange	CH2 = open	SH2 = close

Both pads are located on the soldering side of the CPU card

NOTE: The "Error messages" paragraph gives full details of the instrument behaviour when an out of range condition is displayed.

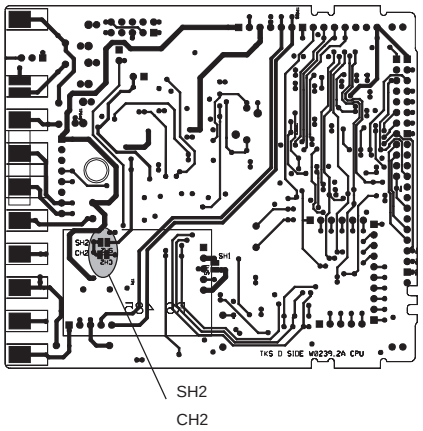


Fig. 12

SELECTION OF THE OUT 1 TYPE

The output 1 can be set, by J303, as SSR output (1- 2) or relay output (2 - 3).
When the relay output is selected, by J302 it is possible to select the contact used (N.O. = 1-2 or N.C = 2-3) as shown below:

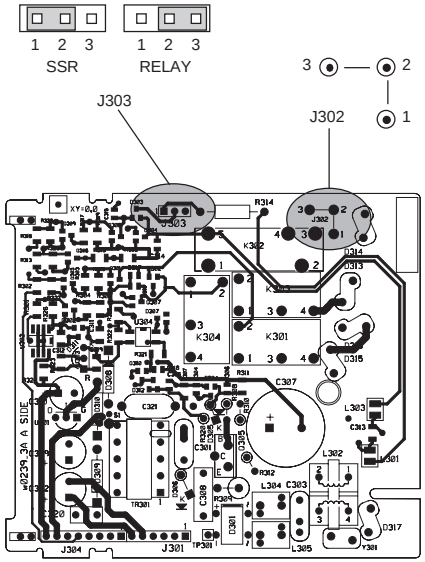


Fig. 16

INSTRUMENT CONFIGURATION

Run time and configuration modes
When the instrument is in run time mode and no modification parameter is in progress, the measured variable is shown on the upper display, while the set point is shown on the lower display (we define this condition "normal display mode").

General note about graphic symbols used for mnemonic code visualization.
The instrument displays some characters with special symbols.
The following table shows the correspondence between the symbols and the characters.

symbol	character
"K"	k
"W"	W
"m"	m
"Z"	Z
"V"	V
"J"	J

CONFIGURATION PROCEDURE

At power up, the instrument starts in the same mode (configuration or run time) it was prior to the power OFF.

When it is desired to go from run-time mode to configuration mode proceed as follows:
a) keep depressed the FUNC pusbutton and push the MAN pushbutton. Maintain the pressure on both pushbuttons for more than 4 seconds, the upper display will show:

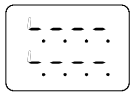
The same indication will be shown when the instrument starts in configuration mode.

b) By the ▲ or ▼ key it is possible to select between:

C.mOn = (monitor) this selection allows to monitor but not to modify the value of all configuration parameters.
C.mOd = (modify) this selection allows to monitor and to modify the value of all configuration parameters.

c) Push the FUNC pushbutton.

NOTES:
1) During monitor mode, the instrument continues to operate as in run time mode and if no push-button is depressed for more than 10 s (or 30 s according to P39 [time out selection"]), the instrument returns automatically to the normal display mode.
2) When modify mode is started, the instrument stops the control and:
   - sets control outputs to OFF;
   - sets alarms in no alarm condition;
   - disables the serial link;
   - the time out will be removed.
3) If the configuration group is protected by security code the display will show:



By ▲ and ▼ keys enter a value equal to the security code set for the configuration mode or the master key (see appendix A.3).
Note: the master key allows to enter in modify configuration parameters mode either if any other configuration security code is set or if the configuration parameters are always protected (P51 = 1).

When it is desired to exit from configuration modify mode proceed as follows:
a) Push "FUNC" or "MAN" push-button more times until the "C.End" parameter is displayed.
b) Pushing "▲" or "▼" push-button select the "YES" indication.

c) Push “FUNC” push-button. The instrument ends the configuration modify mode, preforms an automatic reset and restarts in the run time mode.

Pushbutton function during configuration mode

FUNC = This will memorize the new value of the selected parameter and go to the next parameter (increasing order).

MAN = This will scroll back the parameters without memorization of the new value.

▲ = This will increase the value of the selected parameter

▼ = This will decrease the value of the selected parameter.

CONFIGURATION PARAMETERS

Notes:

1) In the following pages we will describe all the parameters of the instrument but the instrument will show only the parameters related with the specific hardware and in accordance with the specific instrument configuration (i.e. setting OUT 3 equal to 0 (not used), all the parameters related with alarm 2 will be skipped).
2) During configuration mode, the lower display shows the mnemonic code of the selected parameter while the upper display shows the value or the status assigned to the selected parameter.

dF.Cn = Default configuration parameter loading

Available in modify configuration parameters only

OFF = No loading data

tb1 = Loading European Table default parameters.

tb2 = Loading American Table default parameters.

NOTE: the list of both default parameter tables is reported at Appendix A.

SEr1 = Serial interface protocol

OFF = No serial interface
Ero = Polling/selecting ERO
nbUS = Modbus
jbUS = Jbus

SEr2 = Serial link device address

Not available when SEr1 = OFF
From 1 to 95 for ERO protocol
From 1 to 255 for all the other protocols
NOTE: the electrical characteristic of the RS 485 serial interface will allow the connection of 31 devices maximum.

SEr3 = Baud rate for serial link

Not available when SEr1 = OFF
From 600 to 19200 baud.
NOTE: 19200 baud is shown on display as 19.20.

SEr4 = Byte format for serial link

Not available when SEr1 = OFF
7E = 7 bits + even parity (For ERO protocol only)
7O = 7 bits + odd parity (For ERO protocol only)
8E = 8 bits + even parity
8O = 8 bits + odd parity
8 = 8 bits without parity

P1 - Input type and standard range

0	= TC type	L	range	0	/	+400.0 °C
1	= TC type	L	range	0	/	+900 °C
2	= TC type	J	range	-100.0	/	+400.0 °C
3	= TC type	J	range	-100	/	+1000 °C
4	= TC type	K	range	-100.0	/	+400.0 °C
5	= TC type	K	range	-100	/	+1370 °C
6	= TC type	N	range	-100	/	+1400 °C
7	= TC type	R	range	0	/	+1760 °C
8	= TC type	S	range	0	/	+1760 °C
9	= RTD type	Pt 100	range	-199.9	/	+400.0 °C
10	= RTD type	Pt 100	range	-200	/	+800 °C
11	= mV	Linear	range	0	/	60 mV
12	= mV	Linear	range	12	/	60 mV

13	= mA	Linear	range	0	/	20 mA
14	= mA	Linear	range	4	/	20 mA
15	= V	Linear	range	0	/	5 V
16	= V	Linear	range	1	/	5 V
17	= V	Linear	range	0	/	10 V
18	= V	Linear	range	2	/	10 V
19	= TC type	L	range	0	/	+1650 °F
20	= TC type	J	range	-150	/	+1830 °F
21	= TC type	K	range	-150	/	+2500 °F
22	= TC type	N	range	-150	/	+2550 °F
23	= TC type	R	range	0	/	+3200 °F
24	= TC type	S	range	0	/	+3200 °F
25	= RTD type	Pt 100	range	-199.9	/	+400.0 °F
26	= RTD type	Pt 100	range	-330	/	+1470 °F
27	= TC type	T	range	-199.9	/	400.0 °C
28	= TC type	T	range	-330	/	750 °F

NOTE: selecting P1 = 0, 2, 4, 9, 25 or 27, the instrument set automatically P40 = FLtr. For all the remaining ranges it will set P40 = nOFL.

P2 = Decimal point position

This parameter is available only when a linear input is selected (P1 = 11 to 18).

- ----. = No decimal figure.
- ---.- = One decimal figure.
- --.-- = Two decimal figures.
- -.--- = Three decimal figures.

P3 = Initial scale value

For linear inputs it is programmable from -1999 to 4000.
For TC and RTD input it is programmable within the input range.

Notes:

1) When this parameter is modified, rL parameter will be re-aligned to it.
2) If a linear input is selected, the value of this parameter can be greater than P4 in order to get a reverse readout.

P4 = Full scale value

For linear inputs it is programmable from -1999 to 4000.
For TC and RTD inputs, it is programmable within the input range.

Notes:

1) When this parameter is modified, rH parameter will be re-aligned to it.
2) If a linear input is selected, the value of this parameter can be smaller than P3 in order to get a reverse readout.

The initial and full scale values determine the input span which is used by the PID algorithm, the SMART and the alarm functions.

NOTE: the minimum input span (S = P4 - P3), in absolute value, should be set as follows:

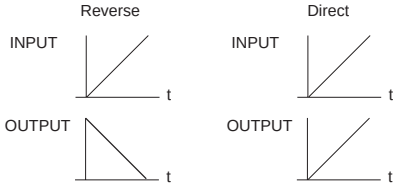
- For linear inputs, S ≥ 100 units.
- For TC input with °C readout, S ≥ 300 °C.
- For TC input with °F readout, S ≥ 550 °F.
- For RTD input with °C readout, S ≥ 100 °C.
- For RTD input with °F readout, S ≥ 200 °F.

P5 = Output 1 type

Changing the P5 setting, also Cy1 parameter will be automatically modified.
rEL = Relay [the cycle time (Cy1) will be forced to 15 s]
SSr = SSR [the cycle time (Cy1) will be forced to 4 s]

P6 = Output 1 action

This parameter is skipped if P7 = 4
rEV = Reverse action (Heating action)
dir = Direct action (Cooling action)



P7 = Output 2 function.
0 = output not used.
1 = it is used as Alarm 1 output and the alarm 1 is programmed as process alarm.
2 = it is used as Alarm 1 output and the alarm 1 is programmed as band alarm.
3 = it is used as Alarm 1 output and the alarm 1 is programmed as deviation alarm.
4 = it is used as secondary control output (Cooling output).
NOTE: setting P7 = 4, the P6 parameter is forced to "rEV".

P8 = Cooling media.
Available only when P7 = 4
- AIr = Air is used as cooling media.
- OIL = Oil is used as cooling media.
- H2O = Direct water is used as cooling media.
Changing P8 parameter, the instrument forces the cycle time and relative cooling gain parameter to the default value related with the chosen cooling media

When	P8 = AIr	- Cy2 = 10 s and rC = 1.00
	P8 = OIL	- Cy2 = 4 s and rC = 0.80
	P8 = H2O	- Cy2 = 2 and rC = 0.40

P9 = Alarm 1 operating mode
Available only when P7 is equal to 1,2 or 3.
H.A. = High alarm (outside for band alarm) with automatic reset.
L.A. = Low alarm (inside for band alarm) with automatic reset.
H.L. = High alarm (outside for band alarm) with manual reset (latched alarm).
L.L. = low alarm (inside for band alarm) with manual reset (latched alarm).

P10 = Current measurement (in Amp.)
(See also "Display function" and "Out 1 failure detection").
OFF = Current measurement disabled
n.O. = Set P10 to n.O. when the load is energized during the ON status of the instrument output (relay energized or SSR output status 1).
n.C. = Set P10 to n.C. when the load is energized during the OFF status of the instrument output (relay de-energized or SSR output status 0).

P11 = Current transformer range
This parameter is present only if P10 is different from OFF.
Programmable from 10 to 100 A.

P12 = Output 3 function
0 = Output not used for alarm 2.
1 = it is used as Alarm 2 output and the alarm 2 is programmed as process alarm.
2 = it is used as Alarm 2 output and the alarm 2 is programmed as band alarm.
3 = it is used as Alarm 2 output and the alarm 2 is programmed as deviation alarm.
NOTE: The output 3 relay operates as a logic OR among the alarm 2, the "Out 1 failure detection" (OFD) function and the "Loop break alarm" (LBA) function.

P13 = Alarm 2 operating mode & type of reset assigned to "Output 1 failure detection" and "Loop Break Alarm" functions.
Available only when P12 is different from 0 or P10 is different from OFF or P47 is different from dIS.
H.A. = High alarm (outside for band alarm) with automatic reset.
L.A. = Low alarm (inside for band alarm) with automatic reset.
H.L. = High alarm (outside band) with manual reset (latched alarm).
L.L. = low alarm (inside band) with manual reset (latched alarm).
NOTE: The "Out 1 failure detection" and "loop break alarm" functions assume only the selected reset type (manual or automatic).

P14 = Output 4 function
0 = Output not used.
1 = it is used as Alarm 3 output and the alarm 3 is programmed as process alarm.
2 = it is used as Alarm 3 output and the alarm 3 is programmed as band alarm.
3 = it is used as Alarm 3 output and the alarm 3 is programmed as deviation alarm.

P15 = Alarm 3 operative mode
Available only when P14 is different from 0.
H.A. = High alarm (outside for band alarm) with automatic reset.
L.A. = Low alarm (inside for band alarm) with automatic reset.
H.L. = High alarm (outside band) with manual reset (latched alarm).
L.L. = low alarm (inside band) with manual reset (latched alarm).

P16 = Programmability of the alarm 3.
Available only when P14 is different from 0.
OPrt = Alarm 3 threshold and hysteresis are programmable in operating mode.
COnF = Alarm 3 threshold and hysteresis are programmable in configuration mode.

P17 = Alarm 3 threshold value
Available only when P14 is different from 0 and P16 is equal to "COnF".
Range:
- For process alarm - within the span limits (P4 - P3)
- For band alarm - from 0 to 500 units.
- For deviation alarm - from -500 to 500 units.

P18 = Alarm 3 hysteresis value
Available only when P14 is different from 0 and P16 is equal to "COnF".
Range: from 0.1% to 10.0 % of the span (P4 - P3)

P19= Soft Start threshold
Threshold value, in eng. units, to initiate the "Soft start" function (output power limiting) at start up.
Range: within the readout span.
NOTE: this threshold value will not be taken into account when tOL = InF.

P20 = Safety lock
0 = No parameter protection. The device is always in unlock condition and all parameters can be modified.
1 = The device is always in lock condition and no one of the parameters (exception made for set points [SP, SP2] and alarm manual reset) can be modified (for SMART status see P31 parameter).
From 2 to 4999 = This combination number is a secret value to be used, in run time (see nnn parameter) to put device in lock/unlock condition.
For SP, SP2 and manual reset of the alarms, the lock/unlock condition has no effect (for SMART status see P31).
From 5000 to 9999 = This combination number is a secret value to be used, in run time (see nnn parameter) to put device in lock/unlock condition.
For SP, SP2, manual reset of the alarm, AL1, AL2, AL3, Hbd and SCA, the lock/unlock condition has no effect (for SMART status see P31).
NOTE: when safety lock is selected, the secret value can not be displayed anymore and the display will show 0, 1, SFt.A (when P20 is encompassed between 2 and 4999) or SFt.b (when P20 is encompassed between 5000 and 9999)

P21 = Alarm 1 action
Available only when P7 is different from 0 or 4.
dir = direct action (relay energized in alarm condition)
rEV = reverse action (relay de-energized in alarm condition)

P22 = Alarm 1 stand-by function (mask)
Available only when P7 is different from 0 or 4.
OFF = stand-by function (mask alarm) disabled
On = stand-by function (mask alarm) enabled
NOTE: If the alarm is programmed as band or deviation alarm, this function masks the alarm condition after a set point change or at the instrument start-up until process variable reaches the alarm threshold plus or minus hysteresis. If the alarm is programmed as a process alarm, this function masks the alarm condition at instrument start-up until the process variable reaches the alarm threshold plus or minus hysteresis.

P23 = action of: the Alarm 2, the "Out 1 failure detection" function and of the "Loop break alarm" function.

Available only when P12 is different from 0 or P10 is different from "OFF" or P47 is different from dIS.
dir = direct (relay energized in alarm condition)
rEV = reverse (relay de-energized in alarm condition)

P24 = Alarm 2 stand-by function (mask alarm)

Available only when P12 is different from 0.
OFF = stand-by function (mask alarm) disabled
On = stand-by function (mask alarm) enabled
NOTE: see NOTE about P22 parameter.

P25 = Alarm 3 action

Available only when P14 is different from 0.
dir = direct (relay energized in alarm condition)
rEV = reverse (relay de-energized in alarm condition)

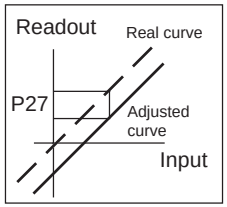
P26 = Alarm 3 stand-by function (mask alarm)

Available only when P14 is different from 0.
OFF = stand-by function (mask alarm) disabled
On = stand-by function (mask alarm) enabled
NOTE: see NOTE about P22 parameter.

P27 = OFFSET applied to the measured value

It allows to set a constant OFFSET throughout the readout range. It is skipped for linear inputs

- For readout ranges with decimal figure, P27 is programmable from -19.9 to 19.9.
- For readout ranges without decimal figure, P27 is programmable from -199 to 199.



P28 = NOT AVAILABLE

P29 = Displayable protected parameters

This parameter is skipped when P20 = 0.
OFF = Protected parameters cannot be displayed.
On = Protected parameter can be displayed.

P30 = MANUAL function

OFF = manual function is disabled
On = manual function can be enabled/ disabled by MAN pushbutton.

P31= SMART function

0 = SMART function disabled.
1 = SMART function is NOT protected by safety lock.
2 = SMART function is under safety lock protection.

P32 = Relative cooling gain calculated by SMART function.

This parameter is available only when P7 = 4 and P31 is different from 0.
OFF = SMART algorithm does not calculate the rC parameter value
On = SMART algorithm calculates the rC parameter value.

P33 = Maximum value of the proportional band calculated by the SMART algorithm.

This parameter is skipped if P31=0.
It is programmable from P34 or P35 value to 100.0 %.

P34 = Minimum value of the proportional band calculated by the SMART algorithm when the instrument has two control outputs.

This parameter is available only when P7 = 4 and P31 is different from 0.
It is programmable from 1.5% to P33 value.

P35 = Minimum value of the proportional band calculated by the SMART algorithm when the instrument has one control output.
This parameter is skipped if P7 = 4 or P31=0.
It is programmable from 1.0 % to P33 value.

P36 = Minimum value of the integral time calculated by the SMART algorithm.
This parameter is skipped if P31=0.
It is programmable from 1 second (00.01) to 2 minutes

P37 = Device status at instrument start up.
This parameter is skipped when P30 = OFF.
0 = the instrument starts in AUTO mode.
1 = It starts in the same way it was prior to the power shut down. If the instrument was in manual mode, the power output will be set to 0.

P38 = NOT AVAILABLE

P39 = Timeout selection
This parameter allows to set the time duration of the timeout for parameter setting used by the instrument during the operating mode.
tn. 10 = 10 seconds
tn 30 = 30 seconds

P40 = Digital filter on the displayed value
It is possible to apply to the displayed value a digital filter of the first order with a time constant equal to:
- 4 s for TC and RTD inputs
- 2 s for linear inputs

noFL. = no filter
FLtr = filter enabled

P41 = Conditions for output safety value
0 = No safety value (see "Error Messages")
1 = Safety value applied when overrange or underrange condition is detected.
2 = Safety value applied when overrange condition is detected.
3 = Safety value applied when underrange condition is detected.

P42 = Output safety value
This parameter is skipped when P41 = 0
This value can be set
- from 0 to 100 % when P7 is different from 4
- from -100 % to 100 % when P7 is equal to 4

P43 = Extension of the anti-reset-wind up
Range: from -30 to +30 % of the proportional band.
NOTE: a positive value increases the high limit of the anti-reset-wind up (over set point) while a negative value decreases the low limit of the anti-reset-wind up (under set point).

P44 = Control action type
Pid - the instrument operates with a PID algorithm.
Pi - the instrument operates with a PI algorithm.

P45 = Set point indication
Fn.SP = during operative mode, when the instrument performs a ramp, it will show the final set point value.
OP.SP = during operative mode, when the instrument performs a ramp, it will show the operative set point.

P46= Operative set point alignment at instrument start up.
0 = At start up, the operative set point will be aligned to SP or SP2 according to the status of the logic input.
1 = At start up, the operative set point will be aligned to the measured value an then it will reach the selected set point with a programmable ramp (see Grd1 and Grd2 operative parameters).
NOTE: if the instrument detects an out of range or an error condition on the measured value it will operate as described for P46 = 0.

P47 = "Loop break alarm" function.

dIS = Alarm not used

Enb = The alarm condition of the "Loop break alarm" (LBA) will be shown by the OUT 3 LED only.

EnbO = The alarm condition of the "Loop break alarm" (LBA) will be shown by the OUT 3 LED and by the OUT 3 relay status.

NOTES:

1) The alarm 2, the Output 1 failure detection and the loop break alarm are in OR condition on the same output (OUT 3).
2) The loop break alarm reset type is programmed by P13 parameter.
3) For more details see "Loop Break Alarm function" at pag 18.

P48 = "Loop break alarm" deviation.

This parameter is available only when P47 is different from dIS.

Programmable from 0 to 500 units

P49 = "Loop break alarm" time.

This parameter is available only when P47 is different from dIS.

Programmable from 00.01 to 40.00 mm.ss.

P50 = "Loop break alarm" hysteresis.

This parameter is available only when P47 is different from dIS.

Programmable from 1to 50% of the power output.

P51 = Security code for configuration parameters

0 No protection (it is always possible to modify all configuration parameters);

1 always protected (it is not possible to modify any configuration parameter);

from 2 to 9999 security code for configuration parameter protection.

Notes:

1) If a value from 2 to 9999 has been assigned as security code it cannot be displayed anymore, when returning on this parameter the display will show "On".
2) If the security code is forgotten a new value can be set.
3) For configuration parameter only is available a passe-partout code, by this code it is possible to enter in modify configuration mode even if the configuration parameters are protected (S.CnF = 1 or from 2 to 9999).

   The passe-partout code is located in Appendix A.
4) Fill out and cut the part of the Appendix A reserved to the security codes if it is desired to keep them secrets.

C. End = End configuration

This parameter allows to come back to the run time mode.

NO = the instrument remains in configuration mode and comes back to the first display of the configuration mode (dF.Cn).

YES = This selection ends the configuration mode. the instrument performs an automatic reset and restart the run time mode.

RUN TIME MODE

DISPLAY FUNCTIONS

The upper display shows the measured value while the lower display shows the programmed set point value (we define the above condition as “normal display mode”).

Note: When the rate of change (Grd1, Grd2) is utilized, the displayed set point value may be different from the operating set point.

It is possible to change the information on the lower display as follows:

- Push the FUNC pushbutton for more than 3 s but less than 10 s. The lower display will show "A." followed by the current consumed by the load (driven by the OUT 1) when the load is in ON condition (see also "OUT 1 failure detection").
- Push "FUNC" pushbutton again. The lower display will show "b." followed by the leakage current running in the load (driven by the OUT 1) when the load is in OFF condition (see also "OUT 1 failure detection").
- Push "FUNC" pushbutton again. The lower display will show "H." followed by OUT 1 power value (from 0 to 100%).
- Push FUNC pushbutton again. The lower display will show "C." followed by OUT 2 power value (from 0 to 100%).
- Push FUNC pushbutton again. The display will return in "Normal Display Mode".

NOTE: The "A.", "b" and "C." informations will be displayed only if the relative function has been previously configured.

When no pushbutton is pressed during the time out (see P39), the display will automatically return in "Normal Display Mode".

In order to keep continuously the desired information on the lower display, depress "▲" or "▼" push- buttons to remove the timeout.

When is desired to return in "Normal Display Mode" push FUNC push-button again.

INDICATORS

°C	Lit when the process variable is shown in Celsius degree.
°F	Lit when the process variable is shown in Fahrenheit degree.
SMRT	Flashing when the first part of the SMART algorithm is active. Lit when the second part of the SMART algorithm is active.
OUT 1	Lit when the OUT 1 is in ON condition.
OUT 2	Lit when OUT 2 is ON or alarm 1 is in the alarm state.
OUT3	Lit when the alarm 2 is in the alarm state. Flashing with slow rate when the "Out 1 failure detection" or/and "Loop break alarm" are in alarm state. Flashing with high rate when the "Out 1 failure detection" **or** "Loop break alarm" is in the alarm state **and** alarm 2 is in alarm state.
OUT4	Lit when the alarm 3 is in alarm condition.
REM	Lit when the instrument is in REMOTE condition (functions and parameters are controlled via serial link).
SPX	Lit when SP2 is used. Flashes when a set point from serial link is used.
MAN	Lit when the instrument is in MANUAL mode.

Pushbutton functionality during operating mode.

FUNC =
- ❑ when the instrument is in "normal display mode"
  1) with a brief pressure (<3 s) it starts the parameter modification procedure.
  2) with a pressure more than 3 s but less than 10s, it changes the indication on the lower display (see "display function").
  3) with a pressure more than 10 s, it enables the "Lamp test" (see "Lamp test")
- ❑ During parameter modification, it allows to memorize the new value of the selected parameter and go to the next parameter (increasing order).

MAN = ❑ when the instrument is in "normal display mode", pushing MAN pushbutton for more than 1 s, it is possible to enable or disable the manual function.
❑ During parameter modification, it allows to scroll back the parameters without memorizing the new setting.

▲ = ❑ During parameter modification, it allows to increase the value of the selected parameter
❑ During MANUAL mode, it allows to increase the output value.

▼ = ❑ During parameter modification, it allows to decrease the value of the selected parameter
❑ During MANUAL mode, it allows to decrease the output value.

▲+MAN = During parameter modification they allow to jump to the maximum programmable value.

▼+MAN = During parameter modification they allow to jump to the minimum programmable value.

▲ + FUNC = During parameter modification they allow to increase the value under modification with higher rate.

▼ + FUNC = During parameter modification they allow to decrease the value under modification with higher rate.

FUNC + MAN = When the instrument is in normal display mode, pushing the two buttons for more than 4 seconds, the instrument will go in configuration mode.

▲ + ▼ = They allow to load the run time default parameters.

NOTE: a 10 or 30 seconds time out (see P 39) can be selected for parameter modification during run time mode. If, during operative parameter modification, no pushbutton is pressed for more than 10 (30) seconds, the instrument goes automatically to the “normal display mode” and the eventual modification of the last parameter will be lost.

ENABLE/DISABLE THE CONTROL OUTPUT

When the instrument is in "normal display mode", by keeping depressed for more than 5 s the ▲ and FUNC pushbuttons, it is possible to disable the control outputs.
In this open loop mode the device will function as an indicator, the lower display will show the word OFF and all control outputs will be in the OFF state.
When the control outputs are disabled the alarms are also in non alarm condition.
The alarms output conditions depend on the alarm action type (see P21-P23-P25).
Depress for more than 5 s the ▲ and FUNC pushbuttons to restore the control status.
The alarm stand-by function, if configured, will be activated as per power up.
If a shut down occurs when the control output is disabled, at instrument power up the control output will be disabled again.

MANUAL FUNCTION

It is possible to enter in MANUAL mode (only if enabled by P30=On) by depressing the MAN pushbutton for more than 1 sec.
The command is accepted and executed only if the display is in "Normal Display Mode".
When in MANUAL mode the LED MAN lights up while the lower display shows the power output values.
The value of OUT 1 is shown by the two most significant digits while the value of OUT 2 (if present) is shown by the two less significant digits.
The decimal point between the two values will be flashing to indicate instrument in MANUAL mode.
Note:

- The graphic symbol " □□ " is used for OUT1 = 100 %
- The graphic symbol " □□ " is used for OUT2 = 100 %

The power output can be modified by using ▲ and ▼ pushbuttons.
By depressing, for more than 2 seconds, MAN pushbutton again the device returns in AUTO mode.

The transfer from AUTO to MANUAL and viceversa is bumpless (this function is not provided if integral action is excluded).
If transfer from AUTO to MANUAL is performed during the first part of SMART algorithm (TUNE) when returning in AUTO the device will be forced automatically to the second part of the SMART algorithm (ADAPTIVE).
At power up the device will be in the AUTO mode or as it was left prior to power shut down depending on P37 configuration selection.
Note: When start up occurs in Manual mode the power output (OUT1 - OUT2) is set to 0.

OUT 1 FAILURE DETECTION FUNCTION
The device is capable (for the load driven by the OUT 1) to measure and display:
- the current running in the load when the load is energized
- the leakage current, flowing through the load, when the load is de-energized.

If the P10 parameter has been correctly set, the instrument generates an alarm when:
- the current running in the load is lower than the "Hbd" parameter value (It shows a partial or total break down of the load, the break down of the actuator or a power down due to a protection or a fuse intervention);
- the leakage current is higher than the "SCA" parameter value (It shows a short circuit of the actuator).

The "Display function" paragraph describes how to show the two current values.
A fault condition is shown by OUT 3 LED flashing and by OUT 3 relay status.
If the ON or OFF period is lower than 400 ms the relative measurement couldn't be performed and the instrument will show flashing the last measured value.

"LOOP BREAK ALARM" FUNCTION
The functioning principle of this alarm is based on the concept that, with a steady load and steady power output, the process rate of rise [deviation (P48)/time (P49)] is steady as well.
Thus, analyzing the process rate of rise of the limit conditions it is possible to estimate the two rates of rise which define the correct process behaviour.
The limit conditions are:
✓ for one control output: 0% and the value of the "OLH" parameter or
✓ for two control outputs: 100% and the value of the "OLH" parameter.

The LBA function is automatically activated when the control algorithm requires the maximum or the minimum power and, if the process response is slower than the estimated rate of rise, the instrument generates an alarm indication in order to show that one or more element of the control loop is in fault condition.
Deviation: from 0 to 500 units.
Timer: from 1 sec. to 40 min.
Hysteresis: from 1% to 50 % of the output span.
NOTES:
1) The LBA does not operate during the soft start.
2) If the instrument operates with the SMART function, the LBA may be operating.
3) For this special function the hysteresis is related with the power output value and not with its rate of rise.

SP/SP2 SELECTION
It is possible to select the operating set point (SP or SP2) only by a logic input (terminals 7 and 8).
By setting P45, it is possible to display the final or the operative set point during a ramp execution.

DIRECT ACCESS TO SET POINT

When the device is in AUTO mode and in “Normal Display Mode”, it is possible to access directly to set point modification (SP or SP2).
Pushing ▲ or ▼ for more than 2 s, the set point will begin changing.
The new setpoint value becomes operative since no pushbutton has been depressed at the end of 2 s timeout.

SERIAL LINK

The device can be connected to a host computer by a serial link.
The host can put the device in LOCAL (functions and parameters are controlled via keyboard) or in REMOTE (functions and parameters are controlled via serial link) mode.
The REMOTE status is signalled by a LED labelled REM.
This instrument allows to modify the run time and configuration parameters via serial link.
The necessary conditions to implement this function are the following:

1) Serial parameters from SEr1 to SEr4 should be properly configured.
2) Device must be in the RUN TIME mode
   During the downloading of configuration the device goes in open loop with all output in OFF state.

At the end of configuration procedure, the device performs an automatic reset and then returns to close loop control.

SMART function

It is used to optimize automatically the control action.
At instrument power up, if the SMART is ON, the second algorithm will be enabled.
To enable the SMART function, push the FUNC pushbutton until "Sñrt" parameter is shown.
Pushing ▲ or ▼ set the display "On" and push the FUNC pushbutton.
The SMRT LED will turn on or flashing according to the selected algorithm.
When the smart function is enabled, it is possible to display but not to modify the control parameters (Pb, ti, td, and rC).
To disable the SMART function, push the FUNC pushbutton again until "Sñrt" parameter is shown.
Pushing ▲ or ▼ set the display "OFF" and push the FUNC pushbutton. The SMRT LED will turn OFF.
The instrument will maintain the current set of control parameter and will enabled parameter modification.
NOTES:

1) When ON/OFF control is programmed (Pb=0), the SMART function is disabled.
2) The SMART enabling/disabling can be protected by safety key (see P31).

LAMP TEST

When it is desired to verify the display efficiency, push FUNC pushbutton for more than 10 s. The instrument will turn ON, with a 50 % duty cycle, all the LEDs of the display (we define this function "LAMP TEST").
No time out is applied to the LAMP TEST.
When it is desired to come back to the normal display mode, push FUNC pushbutton again.
During the lamp test the instrument continues to control the process but no keyboard function is available (exception made for FUNC pushbutton).

RUN TIME PARAMETERS

Push the FUNC pushbutton, the lower display will show the code while the upper display will show the value or the status (On or OFF) of the selected parameter.
By ▲ or ▼ pushbutton it is possible to set the desired value or the desired status.
Pushing the FUNC pushbutton, the instrument memorizes the new value (or the new status) and goes to the next parameter.
Some of the following parameter may be skipped according to the instrument configuration.

Param.	DESCRIPTION
SP	**Set point** (in eng. units). Range: from rL to rH. SP is operative when the logic input is open.
Sñrt	**SMART status**. The On or OFF indication shows the current status of the SMART function (enabled or disabled respectively). Set On to enable the SMART function. Set OFF to disable the SMART function.
n.rSt	**Manual reset of the alarms**. This parameter is skipped if none of the alarms have the manual reset function. Set On and push FUNC to reset the alarms.
SP2	**Set point 2** (in eng. units). Range: from rL to rH. SP2 is operative when the logic input is closed.
nnn	**Software key for parameter protection**. This parameter is skipped if P20 = 0 or 1 On = the instrument is in LOCK condition OFF = the instrument is in UNLOCK condition When it is desired to switch from LOCK to UNLOCK condition, set a value equal to P20 parameter. When it is desired to switch from UNLOCK to LOCK condition, set a value different from P20 parameter.
AL1	**Alarm 1 threshold** This parameter is available only if P 7 is equal to 1, 2 or 3. Ranges: - Span limits for process alarm. - From 0 to 500 units for band alarm. - From -500 to 500 units for deviation alarm.
HSA1	**Alarm 1 hysteresis** This parameter is available only if P 7 is equal to 1, 2 or 3. Range: From 0.1% to 10.0% of the input span or 1 LSD. **Note**: If the hysteresis of a band alarm is larger than the alarm band, the instrument will use an hysteresis value equal to the programmed band minus 1 digit.
AL2	**Alarm 2 threshold** This parameter is available only if P 12 is equal to 1, 2 or 3. For other details see AL1 parameter.
HSA2	**Alarm 2 hysteresis** This parameter is available only if P 12 is equal to 1, 2 or 3. For other details see HSA1 parameter.
AL3	**Alarm 3 threshold** This parameter is available only if P 14 is equal to 1, 2 or 3 and P16 = OPrt. For range details see AL1 parameter.
HSA3	**Alarm 3 hysteresis** This parameter is available only if P 14 is equal to 1, 2 or 3 and P16 = OPrt. For other details see HSA1 parameter.
Pb	**Proportional band** Range: - From 1.0% to 100.0% of the input span when P 7 is different from 4. - From 1.5% to 100.0% of the input span when P 7 is equal to 4. When Pb parameter is set to 0, the control action becomes ON/OFF. **Note**: When device is working with SMART algorithm the Pb value will be limited by P33 and P35 parameters (when P7 is different from 4) or P33 and P34 parameters (when P7 is equal to 4)

HyS **Hysteresis for ON/OFF control action**
Available only when Pb=0.
Range: from 0.1% to 10.0% of the input span.

ti **Integral time**
This parameter is skipped if Pb=0 (ON/OFF action).
Range: from 00.01 to 20.00 [mm.ss]. Above this value the display blanks and integral action is excluded
Note: When the device is working with SMART algorithm, the minimum value of the integral time will be limited by P36 parameter.

td **Derivative time**
This parameter is skipped if Pb=0 (ON/OFF action) or P44 = Pi.
Range: From 00.00 to 10.00 mm.ss.
Note: When device is working with SMART algorithm the td value will be equal to a quarter of Ti value.

IP **Integral pre-load.**
This parameter is skipped if Pb=0 (ON/OFF action).
- For one control output, it is programmable from 0 to 100 % of the output span.
- For two control outputs it is programmable from -100% (100 % cooling) to 100 % (100 % heating)

Cy1 **Output 1 cycle time**
Range: From 1 to 200 s.

Cy2 **Output 2 cycle time**
Available only if P7 is equal to 4.
Range: From 1 to 200 s.

rC **Relative Cooling gain**.
This parameter is skipped if Pb=0 (ON/OFF action) or P7 different from 4.
Range: from 0.20 to 1.00
Note: When the device is working with SMART algorithm and P32 is set to ON the rC value is limited in accordance with the selected type of cooling media:
- from 0.85 to 1.00 when P8 = AIr
- from 0.80 to 0.90 when P8 = OIL
- from 0.30 to 0.60 when P8 = H2O

OLAP **Dead band/Overlap between H/C outputs**.
This parameter is skipped if Pb=0 (ON/OFF action) or P7 different from 4.
Range: from -20 to 50 % of the proportional band.
A negative OLAP value shows a dead band while a positive value shows an overlap.

rL **Set point low limit**
Range: from min. range value (P3) to rH.
Notes:
1) When P3 has been modified, rL will be realigned to it
2) if rL has been modified and the SP (or SP2) value is lower than the new rL value, the SP (or SP2) value will be realigned to it.

rH **Set point high limit**
Range: From rL to full scale value (P4)
Notes:
1) When P4 has been modified, rH will be realigned to it
2) if rH has been modified and the SP (or SP2) value is higher than the new rH value, the SP (or SP2) value will be realigned to it.

Grd1 **Ramp applied to an increasing set point change**
Range: from 1 to 100 digits per minutes.
Above this value the display shows “Inf” meaning that the transfer will be done as a step change.

Grd2 **Ramp applied to a decreasing set point changes**
For other details see Grd1 parameter.

OLH **Output high limit**
Range:
- From 0 to 100 % when device is configured with one control output.
- From -100 to 100% when device is configured with two control outputs.

tOL **Time duration of the output power limiter (Soft start)**
Range: from 1 to 540 min. Above this value the display shows “InF” meaning that the limiting action is always on
Note: The tOL can be modified but the new value will become operative only at the next instrument start up.

Hbd **Threshold value for out 1 break down alarm**
This parameter is skipped if P10=OFF.
Range: From 0 to Full scale value (see P11).
Function: see "Out 1 failure detection".
Note: The threshold resolution will be equal to 0.1 A for range up to 20 A and 1 A for range from 21 A to 100 A.
The hysteresis of this alarm is fixed to 1% of fsv

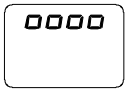
SCA **Threshold value for OUT 1 short circuit alarm**.
This parameter is skipped if P10=OFF.
Range: From 0 to Full scale value (see P11).
Function: see "Out 1 failure detection".
Note: The threshold resolution will be equal to 0.1 A for range up to 20 A and 1 A for range up to 100 A.
The hysteresis of this alarm is fixed to 1% of fsv

rnP **Control output maximum rate of rise**
This parameter is skipped if Pb=0 (ON/OFF action)
It is programmable from 1% to 25% of the output per second.
Above the 25%/s, the display will show "InF" meaning that no ramp is imposed.

ERROR MESSAGES

OVERRANGE, UNDERRANGE AND SENSOR LEADS BREAK INDICATIONS

The device is capable to detect a fault on the process variable (OVERRANGE or UNDERRANGE or SENSOR LEADS BREAK).
When the process variable exceeds the span limits established by configuration parameter P 1 an OVERRANGE condition will be shown on the upper display as in the following figure:



An UNDERRANGE condition will be shown on the upper display as in the following figure:

When P41 is different from zero and an out of range condition is detected, the instrument operates in accordance with P41 and P42 parameters.

When P41 is equal to 0 the following conditions may occur:

- The instrument is set for one output only and an OVERRANGE is detected, the OUT 1 is forced to 0 (if reverse action) or to 100 % (if direct action).
- The instrument is set for heating/cooling action and an OVERRANGE is detected, OUT 1 is forced to 0 and OUT 2 is forced to 100 %.
- The instrument is set for one output only and an UNDERRANGE is detected, the OUT 1 is forced to 100 % (if reverse action) or to 0 (if direct action).
- The instrument is set for heating/cooling action and an UNDERRANGE is detected, OUT 1 is forced to 100 % and OUT 2 is forced to 0.

The sensor leads break can be signalled as:

- for TC/mV input	:	OVERRANGE or UNDERRANGE selected by a solder jumper
- for RTD input	:	OVERRANGE
- for mA/V input	:	UNDERRANGE

Note: On the mA/V input the leads break can be detected only when the range selected has a zero elevation (4/20 mA or 1/5 V or 2/10 V)
On RTD input a special test is provided to signal OVERRANGE when input resistance is less than 15 ohm (Short circuit sensor detection).

ERROR MESSAGES

The instrument performs some self-diagnostic tests. When an error is detected, the instrument shows on the lower display the “Err” indication, while the upper display shows the code of the detected error.

ERROR LIST

SEr	Serial interface parameter error.
100	Write EEPROM error.
200	Attempt to write on protected register.
201 - 2xx	Configuration parameter error. The two less significant digits show the number of the wrong parameter (ex. 209 Err shows an Error on P9 parameter).
301	RTD input calibration error.
305	TC and mV input calibration error.
307	RJ input calibration error.
310	Current transformer input calibration error.
311	Current input (20 mA) calibration error.
312	5 V input calibration error.
313	10 V input calibration error.
400	Operative parameters error
500	Auto-zero error
502	RJ error
510	Error during calibration procedure

NOTES:

1) When a configuration parameter error is detected, it is sufficient to repeat the configuration procedure of the specific parameter.
2) If error 400 is detected, push contemporarily the ▼ and ▲ pushbuttons for loading the default parameters then repeat run time parameter setting.
3) For all the other errors, contact your supplier.

GENERAL INFORMATIONS

GENERAL SPECIFICATIONS

Case: PC black color;
self-extinguishing degree: according to UL 746C
Front protection - designed and tested for IP 65 and NEMA 4X for indoor locations (when panel gasket is installed).
Test were performed in accordance with CEI 70-1 and NEMA 250-1991 STD.
Weight: 360 g.
Power consumption: 5.5 W max.
I**nsulation resistance**: > 100 MΩ according to IEC 1010-1.
Dielectric strength: 2300 V rms according to EN 61010-1.
Display updating time: 500 ms.
Sampling time: 250 ms for linear inputs
500 ms for TC and RTD inputs.
Resolution: 30000 counts.
Accuracy: ± 0.2% f.s.v. ± 1 digit @ 25 °C ambient temperature and nominal power supply voltage.
Common mode rejection: 120 dB at 50/60 Hz.
Normal mode rejection: 60 dB at 50/60 Hz.
Electromagnetic compatibility and safety requirements: This instrument is marked CE.
Therefore, it is conforming to council directives 89/336/EEC (reference harmonized standard EN 50081-2 and EN 50082-2) and to council directives 73/23/EEC and 93/68/EEC (reference harmonized standard EN 61010-1).
Installation category: II
Pollution degree: 2
Temperature drift: (CJ excluded)
< 200 ppm/°C of span for mV and TC ranges 1, 3, 5, 6, 19, 20, 21, 22.
< 300 ppm/°C of span for mA/V
< 400 ppm/°C of span for RTD range 10, 26 and TC range 0, 2, 4, 27 and 28.
< 500 ppm/°C of span for RTD range 9 and TC ranges 7, 8, 23, 24.
< 800 ppm/°C of span for RTD range 25.
Operative temperature: from 0 to 50 °C.
Storage temperature: -20 to +70 °C
Humidity: from 20 % to 85% RH, non condensing.

Protections:
1) WATCH DOG circuit for automatic restart.
2) DIP SWITCH for protection against tampering of configuration and calibration parameters.
Control output updating time:
- 250 ms when a linear input is selected
- 500 ms when a TC or RTD input is selected.

MAINTENANCE

1) REMOVE POWER FROM THE POWER SUPPLY TERMINALS AND FROM RELAY OUTPUT TERMINALS
2) Remove the instrument from case.
3) Using a vacuum cleaner or a compressed air jet (max. 3 kg/cm^2) remove all deposit of dust and dirt which may be present on the louvers and on the internal circuits trying to be careful for not damage the electronic components.
4) To clean external plastic or rubber parts use only a cloth moistened with:
   - Ethyl Alcohol (pure or denatured) [C_2H_5OH] or
   - Isopropil Alcohol (pure or denatured) [$(CH_3)_2CHOH$] or
   - Water (H_2O)
5) Verify that there are no loose terminals.
6) Before re-inserting the instrument in its case, be sure that it is perfectly dry.
7) re-insert the instrument and turn it ON.

APPENDIX A
DEFAULT PARAMETERS

DEFAULT RUN TIME PARAMETERS

PARAMETER	DEFAULT VALUE
SP	= Initial scale value
SnRT	= Disable
n.SRt	= OFF
SP2	= Initial scale value
nnn	= OFF
AL1	= Initial scale value for process alarm 0 for deviation or band alarm
HSA1	= 0.1 %
AL2	= Initial scale value for process alarm 0 for deviation or band alarm
HSA2	= 0.1 %
AL3	= Initial scale value for process alarm = 0 for deviation or band alarm
HSA3	= 0.1 %
PB	= 4.0 %
HyS	= 0.5 %
ti	= 4.00 (4 minutes)
td	= 1.00 (1 minute)
IP	= 30 % if one control output is configured = 0 if two control outputs are configured
Cy1	= 15 seconds for relay output = 4 seconds for SSR output
Cy2	= 10 seconds for P8 = AIr = 4 seconds for P8 = OIL = 2 seconds for P8 = H2O
rC	= 1.00 for P8 = AIr = 0.80 for P8 = OIL = 0.40 for P8 = H2O
OLAP	= 0
rL	= Initial scale value
rH	= Full scale value
Grd 1	= Infinite (step transfer)
Grd 2	= Infinite (step transfer)
OLH	= 100 %
tOL	= Infinite
Hbd	= 50 % of the full scale value
SCA	= 100% of the full scale value
rnP	= Infinite

DEFAULT CONFIGURATION PARAMETERS

PARA.	**TABLE 1**	**TABLE 2**
SEr 1	Ero	Ero
SEr 2	1	1
SEr 3	19200	19200
SEr 4	7E	7E
P1	3	20
P2	----.	----.
P3	0	0
P4	400	1000
P5	rEL	rEL
P6	rEV	rEV
P7	1	1
P8	AIr	AIr
P9	H.A.	H.A.
P10	OFF	OFF
P11	10	10
P12	0	0
P13	H.A	H.A.
P14	0	0
P15	H.A	H.A
P16	OPrt.	OPrt
P17	0	0
P18	0.1	0.1
P19	0	0
P20	0	0
P21	rEV	rEV
P22	OFF	OFF
P23	rEV	rEV
P24	OFF	OFF
P25	rEV	rEV
P26	OFF	OFF
P27	0	0
P28	Not available	Not available
P29	ON	ON
P30	ON	ON
P31	2	2
P32	OFF	OFF
P33	30	30
P34	1.5	1.5
P35	1.0	1.0
P36	00.50	00.50
P37	0	0
P38	Not available	Not available
P39	10	30
P40	nO.FL	nO.FL
P41	0	0
P42	0	0
P43	10	10
P44	PId	PId
P45	Fn.SP	Fn.SP
P46	0	0
P47	diS	diS
P48	50	50
P49	10.00	10.00
P50	10	10
P51	0	0

SECURITY CODES

In this page it is possible to fill out the configuration and the run time security codes of the instrument.

If it is desired to keep the codes secret, cut this page along the dotted line.

Tag name

Run time security code

SSi Super Systems

Model: 31080

Tag number

Configuration security code

Master key

368

Appendix A.2

SSi Super Systems

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